"Die Mannheimsche Kurve von Raumkurven," Monatsh. für Math. u. Phys. 25 (1914), 337-340.

The Mannheim curve of a space curve

By Paul Ernst in Vienna

Translated by D. H. Delphenich

In the study of curves, the method of coordinate conversion has proved to be a fruitful principle for the discovery of new curves and the exhibition of connections between entire families of curves (¹). One of the most useful conversions is the one that takes natural coordinates to rectangular. For any curve, it will produce the so-called Mannheim curve (²), which is the locus of the curvature centers that belong to the respective contact points when the base curve rolls on a line without slipping.

In what follows, the concept of Mannheim curve shall be carried over to space curves.

The form of a space curve is known to be determined completely by the values of the radii of its first and second curvatures ρ and T, when expressed as functions of the arc length *s*. One refers to the givens:

$$\rho = \varphi(s), \qquad T = F(s) \tag{1}$$

as the *natural equations* for the space curve K. The search for the equations of K in rectangular coordinates can come down to the integration of a differential equation of Ricatti type $\binom{3}{2}$.

Let the curve with the equations:

$$y = \varphi(x), \qquad z = F(x) \tag{2}$$

be referred to the Mannheim curve M of the curve M.

The validity of the following theorem can be seen immediately moreover:

If a space curve K rolls along the x-axis of a rectangular coordinate system without slipping in such a way that the x-axis always coincides with the curve tangent and the xyplane always coincides with the osculating plane then the curvature center that belongs to the respective contact point will describe the orthogonal projection M' of M onto the xy-plane, and the torsion center that belongs to the respective contact point will describe

^{(&}lt;sup>1</sup>) Cf., e.g., **B. Wieleitner**, *Spezielle ebene Kurven*, Göschen, Leipzig, 1908. (Sammlung Schubert 56), pp. 313, *et seq.*

^{(&}lt;sup>2</sup>) Wölffing, Zeit. Math. 44 (1899), 140; Mannheim, J. math. pure appl. (2) 4 (1859), 93-104.

^{(&}lt;sup>3</sup>) See, perhaps, **Bianchi**, *Vorlesung über Differenzialgeometrie*, (German translation by **Lukat**), 2nd ed., Teubner, Leipzig, 1903.

the orthogonal projection M'' of M onto the xz-plane, where M means the Mannheim curve of K.

The simplest example is defined by the *ordinary helix:*

$$\rho = \gamma, \quad T = C. \tag{3}$$

Its Mannheim curve reads:

$$y = \gamma, \quad z = C, \tag{3'}$$

so it is therefore a *line* that is parallel to the *x*-axis.

The equations:

$$\rho = as, \qquad T = bs \tag{4}$$

represent the loxodrome of the circular cone. Its Mannheim curve:

$$y = ax, \qquad z = bx \tag{4'}$$

is also a *line*.

The *general helix* (*v.z, the cylindrical loxodrome*) the characterized by the fact that its curvatures have a constant ratio. Its equation is:

$$\frac{\rho}{T} = a,\tag{5}$$

and a curve:

$$\frac{y}{z} = a \tag{6}$$

that lies in a plane that is perpendicular to the *yz*-plane (so it is a *plane curve*) will be its Mannheim curve.

The *skew circles*, which are characterized by constant flexure, also produce *plane curves* as their Mannheim curves.

One also finds the *asymptotic lines of the pseudo-sphere*:

$$\rho = \frac{a}{4} (e^{s/a} + e^{-s/a})T = a \tag{7}$$

amongst the lines of constant torsion.

Their Mannheim curves are planar and are closely related to the *catenary*:

$$y = \frac{1}{2} \cdot \frac{a}{2} (e^{x/a} + e^{-x/a}) z = a , \qquad (7')$$

and they bear the name of *vault lines* (Ger. *Gewölbelinie*) $(^4)$.

As a final example, let the *asymptotic lines to the catenoids* be cited. Their natural equations are:

^{(&}lt;sup>4</sup>) **Schlömilch**, *Übungsbuch zum Studium höheren Analysis*, I. T., 3rd ed., Leipzig, 1879, pp. 101.

$$\rho = s + \frac{2a^2}{s}, \qquad T = a + \frac{s^2}{2a},$$
(8)

which implies the equations:

$$y = x + \frac{2a^2}{x}, \qquad z = a + \frac{s^2}{2a}$$
 (8')

for the Mannheim curve, or more simply:

$$x^{2} - xy + 2a^{2} = 0,$$
 $x^{2} = 2a(z - a).$ (8")

It is then a *space curve of order four and type one* that is defined by the intersection of a hyperbolic cylinder that is perpendicular to the xy-plane and a parabolic one that is perpendicular to the xz-plane. As the elimination of x will show, its perpendicular projection onto the yz-plane is:

$$y^{2}(x-a) - 2a x^{2} = 0, (8^{*})$$

which is a special *tangent curve* to the *parabola* $(^{5})$.

The number of examples can be expanded arbitrarily $(^{6})$.

In the same way as one does for plane curves $(^{7})$, one can also examine space curves that arise from the Mannheim curve when the base curve rolls without slipping along an arbitrary curve, instead of a line, in such a way that the moving triad covers the fixed and moving curves. However, that shall remain a further topic to pursue.

^{(&}lt;sup>5</sup>) **L. Henkel**, Über die aus einer Kurve y = f(x) abgleitete Kurve $y_1 = x \frac{dy}{dx} = x f'(x)$, etc. Dissertation

Marburg 1882.

^{(&}lt;sup>6</sup>) In regard to the examples that were cited here, see: **Cesàro**, *Natürliche Geometrie* (German translation by **Kowalewski**), Teubner, Leipzig, 1901.

^{(&}lt;sup>7</sup>) **L. Braude**, Über einige Verallgemeinerungen des Begriffes der Mannheimschen Kurve, Dissertation, Neumann, Pirmasens, 1911.